

A long-standing problem: Isospin symmetry breaking in the BPS Skyrme model

Carlos Naya Rodríguez

Departamento de Física de Partículas
Universidade de Santiago de Compostela

Solitons, (non) Integrability and Geometry V
Skyrmions - from atomic nuclei to neutron stars

June 20th, 2016 - Krakow, Poland

Index

- 1 Introduction: The isospin symmetry breaking
- 2 Take 1: The isospin-breaking potential
- 3 Take 2: The covariant derivative approach
- 4 Take 3: An isospin-broken solution

Introduction: The isospin symmetry breaking



Introduction: The isospin symmetry breaking

Take 1: The isospin-breaking potential

Take 2: The covariant derivative approach

Take 3: An isospin-broken solution

- **Tony Hilton Royle Skyrme (1922-1987):** Producer



EFT: The Skyrme model (as one of the most popular and successful)

- Baryons as “vortices” in a mesonic fluid \Rightarrow topological solitons, i.e., emergent, *non-perturbative* objects

$$\mathcal{L} = \lambda_0 \mathcal{L}_0 + \underbrace{\lambda_2 \mathcal{L}_2 + \lambda_4 \mathcal{L}_4 + \lambda_6 \mathcal{L}_6}_{\text{massless } \mathcal{L}_{\text{Skyrme}}}$$

$$\underbrace{\hspace{10em}}_{\text{massive } \mathcal{L}_{\text{Skyrme}}}$$

$$\mathcal{L}_2 = -\text{Tr}(L_\mu L^\mu), \quad \mathcal{L}_4 = \text{Tr}([L_\mu, L_\nu]^2), \quad \mathcal{L}_6 = -\pi^4 \mathcal{B}_\mu \mathcal{B}^\mu$$

$$\mathcal{B}^\mu = \frac{1}{24\pi^2} \text{Tr}(\epsilon^{\mu\nu\rho\sigma} L_\nu L_\rho L_\sigma), \quad L_\mu = U^\dagger \partial_\mu U, \quad U \in \text{SU}(2) \cong \mathbb{S}^3$$

- Baryon number \equiv topological charge: $B = \int d^3x \mathcal{B}^0$

The BPS Skyrme model:

$$\mathcal{L}_{06} = -\frac{\lambda^2}{24^2} \text{Tr}(\epsilon^{\mu\nu\rho\sigma} U^\dagger \partial_\mu U U^\dagger \partial_\nu U U^\dagger \partial_\rho U U^\dagger \partial_\sigma U)^2 - \mu^2 \mathcal{U}(\text{Tr} U)$$

- Parametrization of the Skyrme field

$$U = e^{i\xi \vec{n} \cdot \vec{\sigma}} = \cos \xi + i \sin \xi \vec{n} \cdot \vec{\sigma} \quad \vec{n}^2 = 1$$

$$\vec{n} = \frac{1}{1 + |u|^2} (u + \bar{u}, -i(u - \bar{u}), 1 - |u|^2)$$

$$\mathcal{L}_{06} = \frac{\lambda^2 \sin^4 \xi}{(1 + |u|^2)^4} (\epsilon^{\mu\nu\rho\sigma} \xi_\nu u_\rho \bar{u}_\sigma)^2 - \mu^2 \mathcal{U}(\xi)$$

C. Adam, J. Sanchez-Guillen, A. Wereszczynski, Phys. Lett. B **691**, 105 (2010).

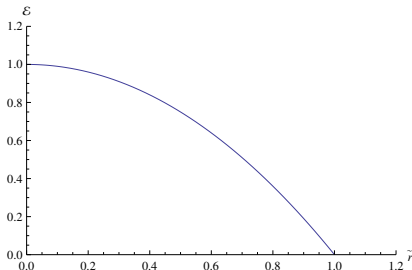
Exact solution: the standard Skyrme potential

$$\mathcal{U} = \mathcal{U}_\pi = \frac{1}{2} \text{Tr}(1 - U) \rightarrow \mathcal{U}(\xi) = 1 - \cos \xi$$

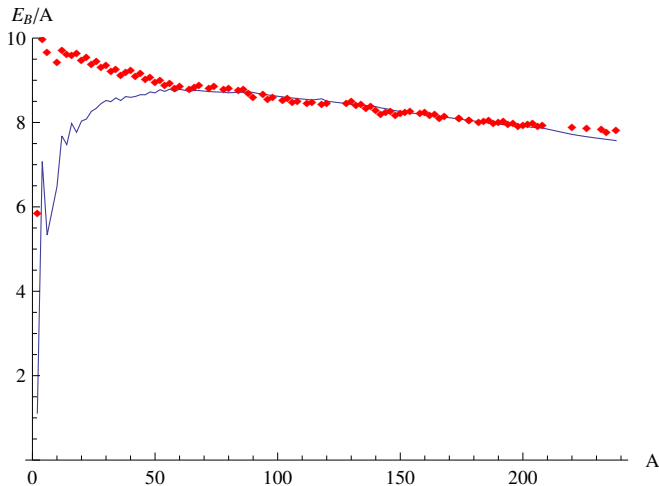
With the ansatz: $\xi = \xi(r)$, $u(\theta, \phi) = \tan \frac{\theta}{2} e^{iB\phi}$

- Compact solution with radius proportional to $B^{1/3}$.
- Energy linear in the baryon number:

$$E = \frac{64\sqrt{2}\pi}{15} \mu\lambda |B|$$



• Nuclear binding energies in the BPS Skyrme model



Contributions to the energy:

- Collective coordinate quantization of spin \vec{J} and isospin \vec{I} (j and $i_3 = (1/2)(Z - N)$ known)

$$U(t, \vec{x}) = A(t)U_0(R_B(t)\vec{x})A^\dagger(t)$$

⇒ Two copies of a symmetric top in the general case.

- Coulomb energies (most important for large B)

$$E_C = \frac{1}{2\epsilon_0} \int d^3x d^3x' \frac{\rho(\vec{r})\rho(\vec{r}')}{4\pi|\vec{r} - \vec{r}'|}$$

- Explicit isospin breaking: $M_n > M_p$

$$\Rightarrow E = E_{\text{sol}} + E_{\text{rot}} + E_C + E_I$$

Isospin breaking:

$$E_1 = a_1 i_3 \quad \text{where} \quad a_1 < 0 \quad \Leftrightarrow \quad M_n > M_p$$

- Binding energy of nucleus $X = {}^A_Z X$, $N = A - Z$:

$$E_{B,X} = ZE_p + NE_n - E_X$$

- Three free parameters λ, μ, a_1 : fit to 3 nuclear masses

$$M_p = 938.272 \text{ MeV}$$

$$M_n - M_p = 1.29333 \text{ MeV}$$

$$M({}^{138}_{56}\text{Ba}) = 137.905 \text{ u} \quad \text{where} \quad \text{u} = 931.494 \text{ MeV}$$

Take 1: The isospin-breaking potential



Isospin-breaking potential: Perturbative contribution to the Lagrangian

$$\mathcal{U}_1 = \frac{\eta^2}{4} \text{Tr}(1 - \tau_3 U \tau_3 U^\dagger)$$

Iso-rotations, $U \rightarrow AUA^\dagger$, are no longer symmetries.

- Small fluctuations of the Skyrme field $U = e^{i\vec{\pi} \cdot \vec{\tau}}$

$$\mu^2 \mathcal{U} = \frac{\mu^2}{2} \text{Tr}(1 - U) \approx \frac{\mu^2}{2} \vec{\pi}^2$$

$$\mathcal{U}_1 = \frac{\eta^2}{4} \text{Tr}(1 - \tau_3 U \tau_3 U^\dagger) \approx \frac{\eta^2}{2} (\pi_1^2 + \pi_2^2 - \pi_3^2)$$

- Mass term (\mathcal{L}_0 contribution):

$$\Rightarrow \mu^2 \mathcal{U} + \mathcal{U}_1 \approx \frac{1}{2} (\mu^2 + \eta^2) (\pi_1^2 + \pi_2^2) + \frac{1}{2} (\mu^2 - \eta^2) \pi_3^2 \quad \checkmark$$

Semiclassical quantization

$$U(\vec{r}, t) = A(t)U_0(R(B(t))\vec{r})A^\dagger(t) = AU_R A^\dagger$$

- Plugging into the \mathcal{U}_I potential

$$\mathcal{U}_I = \frac{\eta^2}{4} \text{Tr}(1 - \tau_3 A U_0 A^\dagger \tau_3 A U_0^\dagger A^\dagger) = \eta^2 \sin \xi [1 - (\vec{R} \cdot \vec{n})^2]$$

with $R_i = R_{3i}(A) = \frac{1}{2} \text{Tr}[\tau_3 A \tau_i A^\dagger]$, i.e. ($A = a_0 + ia_i \tau_i$),

$$R_1 = 2(a_0 a_2 + a_1 a_3), \quad R_2 = 2(a_2 a_3 - a_0 a_1), \quad R_3 = a_0^2 - a_1^2 - a_2^2 + a_3^2$$

- Total contribution to the energy

$$U_I = \frac{4\pi}{3} \frac{32}{35} \frac{|B|\lambda}{\sqrt{2\mu}} \eta^2 \langle N | 3 - R_1^2 - R_2^2 - R_3^2 | N \rangle = \frac{8\pi}{3} \frac{32}{35} \frac{|B|\lambda}{\sqrt{2\mu}} \neq \mathcal{U}_I(i_3) \quad \times$$

Take 2: The covariant derivative approach



New terms: Perturbative inclusion of Dirichlet + Isospin-breaking

$$\mathcal{L}_2 - \mathcal{U}_1 = -\alpha \text{Tr}(L_\mu L^\mu) - \frac{\eta^2}{4} \text{Tr}(1 - \tau_3 U \tau_3 U^\dagger)$$

- For static solutions U_0

$$\mathcal{L}_2 - \mathcal{U}_1 = -\alpha \text{Tr}(U_0^\dagger D_\mu U_0 U_0^\dagger D^\mu U_0)$$

- Covariant derivative

$$D_\mu U_0 = \partial_\mu U_0 + i \frac{\omega}{2} [\tau_3, U_0] \delta_{\mu 0}$$

with ω defined as

$$\omega^2 = -\frac{\eta^2}{2\alpha}$$

- Equivalent to introduce an iso-rotated field

$$\tilde{U} = TU_0T^\dagger \in \text{SU}(2)$$

by the time-dependent SU(2) matrix

$$T = \begin{pmatrix} e^{i\frac{\omega t}{2}} & 0 \\ 0 & e^{-i\frac{\omega t}{2}} \end{pmatrix} = \cos \frac{\omega t}{2} + i\tau_3 \sin \frac{\omega t}{2}$$

E. Rathske, Z. Phys. A **331**, 499 (1988)

$$\Rightarrow U_0^\dagger D_\mu U_0 = \tilde{U}^\dagger \partial_\mu \tilde{U}$$

- Re-write the perturbative contribution

$$\tilde{\mathcal{L}}_2 = \mathcal{L}_2 - \mathcal{U}_1 = -\alpha \text{Tr}(\tilde{U}^\dagger \partial_\mu \tilde{U} \tilde{U}^\dagger \partial^\mu \tilde{U})$$

makes life easy (quantization)!

Semiclassical quantization

- Usual time-dependent rotations and iso-rotations

$$U_0(\vec{r}) \rightarrow U(\vec{r}, t) = A(t)U_0(R(B(t))\vec{r})A^\dagger(t) = AU_R A^\dagger$$

- Iso-rotations and Euler angles

$$A = a_0 + i\vec{a} \cdot \vec{\tau} = V_3(\alpha)V_2(\beta)V_3(\gamma)$$

- Usual parametrization of the BPS part, \mathcal{L}_{06} .
- Usual parametrization of the perturbative part, $\tilde{\mathcal{L}}_2$, but with a modified A matrix

$$\tilde{A} = TA = V_3(\alpha + \omega t)V_2(\beta)V_3(\gamma)$$

- Shifted isospin velocities

$$\tilde{A}^\dagger \dot{\tilde{A}} = i(\vec{\mathcal{W}} + \vec{D}) \cdot \frac{\vec{\tau}}{2}$$

with $D = \omega(R_1, R_1, R_3), \quad R_i = R_{3i}(A) = \frac{1}{2}\text{Tr}[\tau_3 A \tau_i A^\dagger]$

- Perturbative contribution

$$\begin{aligned}\tilde{\mathcal{L}}_2 = & \mathcal{W}_i \left[-\alpha \text{Tr}(T_i T_j) \right] \mathcal{W}_j + 2\mathcal{W}_i \left[-\alpha \epsilon_{jkl} x_k \text{Tr}(T_i L_l) \right] \omega_j \\ & + \omega_j \left[-\alpha \epsilon_{ikl} \epsilon_{jmn} x_k x_m \text{Tr}(L_l L_n) \right] \omega_j + D_i \left[-\alpha \text{Tr}(T_i T_j) \right] D_j \\ & + 2\mathcal{W}_i \left[-\alpha \text{Tr}(T_i T_j) \right] D_j + 2D_i \left[-\alpha \epsilon_{jkl} x_k \text{Tr}(T_i L_l) \right] \omega_j - \mathcal{E}_2.\end{aligned}$$

- BPS contribution

$$\begin{aligned}\mathcal{L}_{60} = & \mathcal{W}_i \left[\frac{9\lambda^2}{24^2} \text{Tr}(\epsilon^{pqr} T_i L_q L_r) \text{Tr}(\epsilon^{pst} T_j L_s L_t) \right] \mathcal{W}_j \\ & + 2\mathcal{W}_i \left[\frac{18\lambda^2}{24^2} \epsilon_{jkl} x_k \text{Tr}(\epsilon^{pqr} T_i L_q L_r) \text{Tr}(\epsilon^{pst} L_l L_s L_t) \right] \omega_j \\ & + \omega_j \left[\frac{9\lambda^2}{24^2} \epsilon_{ikl} \epsilon_{jmn} x_k x_m \text{Tr}(\epsilon^{pqr} L_l L_q L_r) \text{Tr}(\epsilon^{pst} L_n L_s L_t) \right] \omega_j - \mathcal{E}_0,\end{aligned}$$

Total Lagrangian

$$L = \frac{1}{2} \mathcal{W}_i \mathcal{I}_{ij} \mathcal{W}_j - \mathcal{W}_i \mathcal{K}_{ij} \omega_{ij} + \frac{1}{2} \omega_i \mathcal{J}_{ij} \omega_j + \mathcal{W}_i A_i + \omega_i B_i - U_1 - E,$$

- Additional contributions

$$A_i = -2\alpha D_j \int d^3x \text{Tr}(T_i T_j)$$

$$B_i = -2\alpha D_j \epsilon_{ikl} \int d^3x x_k \text{Tr}(T_j L_l)$$

$$V_l = \alpha D_i D_j \int d^3x \text{Tr}(T_i T_j)$$

$$E = E_0 + E_2$$

- Moments of inertia tensors

$$\mathcal{I}_{ij} = \int d^3x \left[-2\alpha \text{Tr}(T_i T_j) + \frac{18\lambda^2}{24^2} \text{Tr}(\epsilon^{pqr} T_i L_q L_r) \text{Tr}(\epsilon^{pst} T_j L_s L_t) \right]$$

$$\mathcal{J}_{ij} = \epsilon_{ikl} \epsilon_{jmn} x_k x_m \int \left[-2\alpha \text{Tr}(L_l L_n) + \frac{18\lambda^2}{24^2} \text{Tr}(\epsilon^{pqr} L_l L_q L_r) \text{Tr}(\epsilon^{pst} L_n L_s L_t) \right]$$

$$\mathcal{K}_{ij} = \epsilon_{jkl} x_k \int d^3x \left[2\alpha \text{Tr}(T_i L_l) - \frac{18\lambda^2}{24^2} \text{Tr}(\epsilon^{pqr} T_i L_q L_r) \text{Tr}(\epsilon^{pst} L_l L_s L_t) \right]$$

- Canonical momenta

$$K_i = \frac{\partial L}{\partial \mathcal{W}_i} = \mathcal{I}_{ij} \mathcal{W}_j - \mathcal{K}_{ij} \omega_j + A_i \quad L_i = \frac{\partial L}{\partial \omega_i} = -\mathcal{W}_j \mathcal{K}_{ji} + \mathcal{J}_{ij} \omega_j + B_i$$

- Hamiltonian

$$H = K_i \mathcal{W}_i + L_i \omega_i - L = K_i \mathcal{W}_i + L_i \omega_i - \frac{1}{2} \mathcal{W}_i \mathcal{I}_{ij} \mathcal{W}_j + \mathcal{W}_i \mathcal{K}_{ij} \omega_j - \frac{1}{2} \omega_i \mathcal{J}_{ij} \omega_j - \mathcal{W}_i A_i - \omega_i B_i + U_I + E$$

which after substituting the angular velocities reads

$$H = \frac{1}{2} \sum_{i=1}^3 \left[\frac{(L_i + \mathcal{K}_i \frac{K_i}{\mathcal{I}_i})^2}{\mathcal{J}_i - \frac{\mathcal{K}_i^2}{\mathcal{I}_i}} + \frac{K_i^2}{\mathcal{I}_i} + \frac{(B_i + \mathcal{K}_i \frac{A_i}{\mathcal{I}_i})^2}{\mathcal{J}_i - \frac{\mathcal{K}_i^2}{\mathcal{I}_i}} + \frac{A_i^2}{\mathcal{I}_i} - \frac{1}{\mathcal{I}_i - \frac{\mathcal{K}_i^2}{\mathcal{J}_i}} K_i A_i - \frac{\mathcal{K}_i}{\mathcal{I}_i \mathcal{J}_i - \mathcal{K}_i^2} K_i B_i - \frac{\mathcal{K}_i}{\mathcal{I}_i \mathcal{J}_i - \mathcal{K}_i^2} L_i A_i - \frac{1}{\mathcal{J}_i - \frac{\mathcal{K}_i^2}{\mathcal{I}_i}} L_i B_i \right] + U_I + E$$

Axially symmetric ansatz:

$$U = \cos \xi + i \sin \xi \vec{n} \cdot \vec{\tau}, \quad \xi = \xi(r), \quad \vec{n} = (\sin \theta \cos B\phi, \sin \theta \sin B\phi, \cos \theta)$$

- Additional contributions

$$A_i = \frac{32}{3} \pi \alpha \omega R_i \int dr r^2 \sin^2 \xi$$

$$B_1 = B_2 = 0, \quad B_3 = -\frac{32\pi}{3} \alpha \omega B R_3 \int d^3 x r^2 \sin^2 \xi$$

$$B = 1$$

$$B_i = -\frac{32\pi}{3} \alpha \omega R_i \int dr r^2 \sin^2 \xi$$

- Moments of inertia tensors

$$\mathcal{I}_1 = \mathcal{I}_2 = \int \left[\frac{32\pi}{3} \alpha \sin^2 \xi + \frac{1 + 3n^2}{3r^2} \pi \lambda^2 \xi_r^2 \sin^4 \xi \right] r^2 dr$$

$$\mathcal{I}_3 = \int \left[\frac{32\pi}{3} \alpha \sin^2 \xi + \frac{4}{3r^2} \pi \lambda^2 \xi_r^2 \sin^4 \xi \right] r^2 dr$$

$$\mathcal{J}_1 = \mathcal{J}_2 = \int \left[\frac{8}{3} (3 + B^2) \pi \alpha \sin^2 \xi + \frac{4}{3r^2} \pi \lambda^2 B^2 \xi_r^2 \sin^4 \xi \right] r^2 dr$$

$$\mathcal{J}_3 = B\mathcal{K}_3 = B^2\mathcal{I}_3, \quad \mathcal{K}_1 = \mathcal{K}_2 = 0$$

$B = 1$

$$\mathcal{I}_1 = \mathcal{I}_2 = \mathcal{I}_3 = \int \left[\frac{32\pi}{3} \alpha \sin^2 \xi + \frac{4}{3r^2} \pi \lambda^2 \xi_r^2 \sin^4 \xi \right] r^2 dr$$

$$\mathcal{J}_1 = \mathcal{J}_2 = \mathcal{J}_3 = \mathcal{K}_1 = \mathcal{K}_2 = \mathcal{K}_3 = \mathcal{I}_1$$

- Canonical momenta

$$\vec{K} = (\mathcal{I}_1 \mathcal{W}_1 + A_1, \mathcal{I}_1 \mathcal{W}_2 + A_2, \mathcal{I}_3 (\mathcal{W}_3 - B\omega_3) + A_3)$$

$$\vec{L} = (\mathcal{J}_1 \omega_1, \mathcal{J}_1 \omega_2, -B\mathcal{I}_3 (\mathcal{W}_3 - B\omega_3) - BA_3)$$

- Hamiltonian

$$H = E + U_I + \frac{1}{2} \left[\frac{\vec{L}^2}{\mathcal{J}_1} + \frac{1}{\mathcal{I}_1} (\vec{K} - \vec{A})^2 + \left(\frac{1}{\mathcal{I}_3} - \frac{1}{\mathcal{I}_1} \right) (K_3 - A_3)^2 - \frac{B^2}{\mathcal{J}_1} K_3^2 \right]$$

$$(\vec{K} - \vec{A})^2 = \vec{K}^2 + \vec{A}^2 - 2\vec{K} \cdot \vec{A} = \vec{K}^2 + A^2 + 2A I_3$$

where $A_i = A R_i$, $A = \frac{32}{3} \pi \alpha \omega \int dr r^2 \sin^2 \xi$

Problem!

Covariant derivative \equiv Isospin chemical potential

PHYSICAL REVIEW D **78**, 034040 (2008)

Skyrmion semiclassical quantization in the presence of an isospin chemical potential

Thomas D. Cohen*

Department of Physics, University of Maryland, College Park, Maryland 20742-4111, USA

Juan A. Ponciano*

*CEFIMAS, Avenida Santa Fe 1145, (1059) Buenos Aires, Argentina; CONICET, Rivadavia 1917, (1033) Buenos Aires, Argentina;
and Universidad Nacional de La Plata, C.C. 67, (1900) La Plata, Argentina*

Norberto N. Scoccola†

*Physics Department, Comisión Nacional de Energía Atómica, (1429) Buenos Aires, Argentina;
CONICET, Rivadavia 1917, (1033) Buenos Aires, Argentina;
and Universidad Favaloro, Solís 453, (1078) Buenos Aires, Argentina*

(Received 7 May 2008; published 29 August 2008)

The semiclassical description of Skyrmions at small isospin chemical potential μ_I is carefully analyzed. We show that when the calculation of the energy of a nucleon is performed using the straightforward generalization of the vacuum sector techniques ($\mu_I = 0$), together with the “natural” assumption $\mu_I = \mathcal{O}(N_c^2)$, the proton and neutron masses are nonlinear in μ_I in the regime $|\mu_I| < m_\pi$. Although these nonlinearities turn out to be numerically quite small, such a result fails to strictly agree with the very robust prediction that for those values of μ_I the energy excitations above the vacuum are linear in μ_I . The resolution of this paradox is achieved by studying the realization of the large N_c limit of QCD in the Skyrme model at finite μ_I . This is done in a simplified context devoid of the technical complications present in the Skyrme model but which fully displays the general scaling behavior with N_c . The analysis shows that the paradoxical result appears as a symptom of using the semiclassical approach beyond its regime of validity and that, at a formal level, the standard methods for dealing with the Skyrme model are only strictly justified for states of high isospin, $I \sim N_c$.

DOI: 10.1103/PhysRevD.78.034040

PACS numbers: 12.39.Dc, 25.75.Nq

Take 3: An isospin-broken solution



New potential for the BPS Skyrme model:

$$\begin{aligned} \mathcal{U} &= \frac{1}{2} \text{Tr}(1 - U) + \epsilon^2 \frac{1}{2} \frac{\text{Tr}(1 - \tau_3 U \tau_3 U^\dagger)}{\text{Tr}(1 + U)} \\ &= 2 \sin^2 \left(\frac{\xi}{2} \right) (1 + \epsilon(1 - n_3^2)) \neq \mathcal{U}(r) \end{aligned}$$

- BPS equation

$$\frac{\lambda^2}{r^2} \sin^4 \xi \xi_r^2 \left(\frac{i \epsilon_{ij} \nabla_i u \nabla_j \bar{u}}{(1 + |u|^2)^2} \right)^2 = \mu^2 u$$

- Assuming $u = v(\theta) e^{i\phi}$

$$\alpha^2 \frac{\lambda^2}{r^4} \sin^4 \xi \xi_r^2 = 2\mu^2 \sin^2 \left(\frac{\xi}{2} \right)$$

$$\frac{1}{\alpha^2} \left(\frac{2v v_\theta}{\sin \theta (1 + v^2)^2} \right)^2 = 1 + \epsilon^2 (1 - n_3^2)$$

Exact static solution for $B = 1$

- Profile function

$$\xi = \begin{cases} 2 \arccos\left(\frac{r}{R}\right) & r \in [0, R] \\ 0 & r \geq R \end{cases} \quad R = \left(\frac{4\sqrt{2}\alpha\lambda}{\mu}\right)^{1/3}$$

- Angular part

$$\frac{1}{1+v^2} = \frac{1}{2\epsilon} \left(1 + \sqrt{2} \sin \left[\frac{1}{2} \left(\beta - \frac{\pi}{2} + \beta \cos \theta \right) \right] \right)$$

with

$$\beta = \arcsin\left(\frac{2\epsilon - 1}{\sqrt{2}}\right) + \frac{\pi}{4}, \quad \alpha = \frac{\beta}{4\epsilon}$$

- Limit $\epsilon \rightarrow 0 \Rightarrow \alpha = 1/2$

$$\xi = \arccos \left[\left(\frac{\mu}{2\sqrt{2}\lambda} \right)^{1/3} r \right], \quad v = \tan \frac{\theta}{2}$$

Semiclassical quantization: Please, proceed as always

- Moments of inertia tensors

$$\mathcal{I}_{ij} = \frac{\lambda^2}{2} \int \xi_r^2 \sin^4 \xi \partial_i n_j \partial_l n_j d^3x$$

$$\mathcal{J}_{ij} = \frac{\lambda^2 \beta^2}{4 \epsilon^2} \int \frac{1}{r^4} \xi_r^2 \sin^4 \xi \cos^2 \theta (r^2 \delta_{ij} - x_i x_j) r^2 \sin \theta dr d\theta d\phi$$

$$\mathcal{K}_{ij} = -\frac{\lambda^2}{2} \int \xi_r^2 \sin^4 \xi \epsilon_{jkl} \epsilon_{def} x_k \partial_s n_i n_d \partial_s n_e \partial_l n_f d^3x$$

- Radial integration

$$\int \xi_r^2 \sin^4 \xi dr = \frac{64 \cdot 2^{5/6}}{35} \left(\frac{\epsilon \mu}{\beta \lambda} \right)^{1/3}$$

Symmetries

$$\mathcal{I}_{11} = \mathcal{I}_{22} \neq \mathcal{I}_{33}, \quad \mathcal{J}_{11} = \mathcal{J}_{22} \neq \mathcal{J}_{33}, \quad \mathcal{K}_{11} = \mathcal{K}_{22} \neq \mathcal{K}_{33}$$

$$\mathcal{I}_{11} \neq \mathcal{J}_{11} \neq \mathcal{K}_{11}, \quad \mathcal{I}_{33} = \mathcal{J}_{33} = \mathcal{K}_{33}$$

Examples for different ϵ

- $\epsilon = 0.1$

$$\mathcal{I}_{ij} = \lambda^2 \left(\frac{\mu}{\lambda} \right)^{1/3} \begin{pmatrix} 11.122 & 0 & 0 \\ 0 & 11.122 & 0 \\ 0 & 0 & 11.1604 \end{pmatrix}$$

$$\mathcal{J}_{ij} = \lambda^2 \left(\frac{\mu}{\lambda} \right)^{1/3} \begin{pmatrix} 11.1546 & 0 & 0 \\ 0 & 11.1546 & 0 \\ 0 & 0 & 11.1604 \end{pmatrix}$$

$$\mathcal{K}_{ij} = \lambda^2 \left(\frac{\mu}{\lambda} \right)^{1/3} \begin{pmatrix} 11.1301 & 0 & 0 \\ 0 & 11.1301 & 0 \\ 0 & 0 & 11.1604 \end{pmatrix}$$

Examples for different ϵ

- $\epsilon = 0.5$

$$\mathcal{I}_{ij} = \lambda^2 \left(\frac{\mu}{\lambda}\right)^{1/3} \begin{pmatrix} 11.5889 & 0 & 0 \\ 0 & 11.5889 & 0 \\ 0 & 0 & 12.0541 \end{pmatrix}$$

$$\mathcal{J}_{ij} = \lambda^2 \left(\frac{\mu}{\lambda}\right)^{1/3} \begin{pmatrix} 11.7519 & 0 & 0 \\ 0 & 11.7519 & 0 \\ 0 & 0 & 12.0541 \end{pmatrix}$$

$$\mathcal{K}_{ij} = \lambda^2 \left(\frac{\mu}{\lambda}\right)^{1/3} \begin{pmatrix} 11.6282 & 0 & 0 \\ 0 & 11.6282 & 0 \\ 0 & 0 & 12.0541 \end{pmatrix}$$

- Canonical momenta

$$K_i = \frac{\partial L}{\partial \mathcal{W}_i} \Rightarrow \vec{K} = (\mathcal{I}_1 \mathcal{W}_1 - \mathcal{K}_1 \omega_1, \mathcal{I}_1 \mathcal{W}_2 - \mathcal{K}_1 \omega_2, \mathcal{I}_3 (\mathcal{W}_3 - \omega_3))$$

$$L_i = \frac{\partial L}{\partial \omega_i} \Rightarrow \vec{L} = (\mathcal{J}_1 \omega_1 - \mathcal{K}_1 \mathcal{W}_1, \mathcal{J}_1 \omega_2 - \mathcal{K}_1 \mathcal{W}_2, \mathcal{I}_3 (\omega_3 - \mathcal{W}_3))$$

Remember! Body-fixed operators!

$$l_i = -R_{ij}(A)K_j, \quad J_i = -R_{ij}(B)^T L_j \quad \left(R_{ij}(A) = \frac{1}{2} \text{Tr}[\tau_i A \tau_j A^\dagger] \right)$$

- Hamiltonian

$$\mathcal{H}_{\text{rot}} = \frac{1}{2} \left\{ \frac{1}{\mathcal{J}_1 - \frac{\mathcal{K}_1^2}{\mathcal{I}_1}} \left[(L_1 + \frac{\mathcal{K}_1}{\mathcal{I}_1} K_1)^2 + (L_2 + \frac{\mathcal{K}_1}{\mathcal{I}_1} K_2)^2 \right] + \frac{K_1^2}{\mathcal{I}_1} + \frac{K_2^2}{\mathcal{I}_1} + \frac{K_3^2}{\mathcal{I}_3} \right\}$$

- Hamiltonian 1

$$\mathcal{H}_{\text{rot}} = \frac{1}{2} \left[\frac{\vec{L}^2}{\mathcal{I}_1 - \frac{\mathcal{K}_1^2}{\mathcal{I}_1}} + \frac{\vec{K}^2}{\mathcal{I}_1 - \frac{\mathcal{K}_1}{\mathcal{I}_1}} + \left(\frac{1}{\mathcal{I}_3} - \frac{\mathcal{I}_1 + \mathcal{J}_1 - 2\mathcal{K}_1}{\mathcal{I}_1 \mathcal{J}_1 - \mathcal{K}_1^2} \right) \mathcal{K}_3^2 \right] + \frac{\mathcal{K}_1}{\mathcal{I}_1 \mathcal{J}_1 - \mathcal{K}_1^2} \vec{L} \cdot \vec{K}$$

- Hamiltonian 2

$$\mathcal{H}_{\text{rot}} = \frac{1}{2} \left[\frac{\mathcal{K}_1}{\mathcal{I}_1 \mathcal{J}_1 - \mathcal{K}_1^2} \vec{M}^2 + \frac{\mathcal{I}_1 - \mathcal{K}_1}{\mathcal{I}_1 \mathcal{J}_1 - \mathcal{K}_1^2} \vec{L}^2 + \frac{\mathcal{J}_1 - \mathcal{K}_1}{\mathcal{I}_1 \mathcal{J}_1 - \mathcal{K}_1^2} \vec{K}^2 + \left(\frac{1}{\mathcal{I}_3} - \frac{\mathcal{I}_1 + \mathcal{J}_1 - 2\mathcal{K}_1}{\mathcal{I}_1 \mathcal{J}_1 - \mathcal{K}_1^2} \right) \mathcal{K}_3^2 \right]$$

Grand spin

$$\vec{M} = \vec{L} + \vec{K} \Rightarrow \vec{M}^2 = \vec{L}^2 + \vec{K}^2 + 2\vec{L} \cdot \vec{K}$$

Hamiltonian 1: Calculation of the scalar product $\vec{L} \cdot \vec{K}$

$$\vec{K} \cdot \vec{L} = \frac{1}{2}K_+L_- + \frac{1}{2}K_-L_+ + K_3L_3$$

- Ladder operators

$$K_+ = K_1 + iK_2, \quad K_- = K_1 - iK_2, \quad L_+ = L_1 + iL_2, \quad L_- = L_1 - iL_2$$

- Action on an arbitrary state

$$K_{\pm}|i, i_3, k_3\rangle \otimes |j, j_3, l_3\rangle = \sqrt{i(i+1) - k_3(k_3 \pm 1)} |i, i_3, k_3 \pm 1\rangle \otimes |j, j_3, l_3\rangle$$

$$K_3|i, i_3, k_3\rangle \otimes |j, j_3, l_3\rangle = k_3|i, i_3, k_3\rangle \otimes |j, j_3, l_3\rangle$$

$$L_{\pm}|i, i_3, k_3\rangle \otimes |j, j_3, l_3\rangle = \sqrt{j(j+1) - l_3(l_3 \pm 1)} |i, i_3, k_3\rangle \otimes |j, j_3, l_3 \pm 1\rangle$$

$$L_3|i, i_3, k_3\rangle \otimes |j, j_3, l_3\rangle = l_3|i, i_3, k_3\rangle \otimes |j, j_3, l_3\rangle$$

General nucleon state

$$|N\rangle = |1/2, i_3, k_3\rangle \otimes |1/2, j_3, l_3\rangle$$

- Non-vanishing actions

$$K_+ L_- |1/2, i_3, -1/2\rangle \otimes |1/2, j_3, 1/2\rangle = |1/2, i_3, 1/2\rangle \otimes |1/2, j_3, -1/2\rangle$$

$$K_- L_+ |1/2, i_3, 1/2\rangle \otimes |1/2, j_3, -1/2\rangle = |1/2, i_3, -1/2\rangle \otimes |1/2, j_3, 1/2\rangle$$

$$K_3 L_3 |1/2, i_3, k_3\rangle \otimes |1/2, j_3, l_3\rangle = k_3 l_3 |1/2, i_3, k_3\rangle \otimes |1/2, j_3, l_3\rangle$$

Constraint $k_3 = -l_3$ is always fulfilled!

- Matrix element

$$\langle N | \vec{K} \cdot \vec{L} | N \rangle = \langle N | K_3 L_3 | N \rangle = k_3 l_3 = -\frac{1}{4}$$

Impossible to distinguish proton from neutron!

General nucleon state

$$|N\rangle = \frac{1}{\sqrt{2}} (|1/2, i_3, 1/2\rangle \otimes |1/2, j_3, -1/2\rangle + e^{i\alpha} |1/2, i_3, -1/2\rangle \otimes |1/2, j_3, 1/2\rangle)$$

- Different actions

$$K_+ L_- |N\rangle = \frac{e^{i\alpha}}{\sqrt{2}} |1/2, i_3, 1/2\rangle \otimes |1/2, j_3, -1/2\rangle$$

$$K_- L_+ |N\rangle = \frac{1}{\sqrt{2}} |1/2, i_3, -1/2\rangle \otimes |1/2, j_3, 1/2\rangle$$

$$K_3 L_3 |N\rangle = -\frac{1}{4} |N\rangle$$

- Matrix element

$$\langle N | \vec{K} \cdot \vec{L} | N \rangle = \frac{e^{i\alpha}}{4} + \frac{e^{-i\alpha}}{4} - \frac{1}{4} = \frac{1}{2} \cos \alpha - \frac{1}{4}$$

$$\text{if } \left. \begin{array}{l} \alpha = \pi \rightarrow \text{proton} \\ \alpha = 0 \rightarrow \text{neutron} \end{array} \right\} \Rightarrow \langle N | \vec{K} \cdot \vec{L} | N \rangle = -i_3 - \frac{1}{4}$$

Hamiltonian 2: Composition of grand spin \vec{M}

$$\vec{M} = \vec{K} + \vec{L} \Rightarrow m = 0, 1$$

- Corresponding states

$$|m, m_3\rangle \sim |i, k_3\rangle \otimes |j, l_3\rangle$$

- Two different states fulfilling $m_3 = k_3 + l_3 = 0$

$$|0, 0\rangle = \frac{1}{\sqrt{2}} (|1/2, 1/2\rangle \otimes |1/2, -1/2\rangle - |1/2, -1/2\rangle \otimes |1/2, 1/2\rangle)$$

$$|1, 0\rangle = \frac{1}{\sqrt{2}} (|1/2, 1/2\rangle \otimes |1/2, -1/2\rangle + |1/2, -1/2\rangle \otimes |1/2, 1/2\rangle)$$

$$\text{if } \left. \begin{array}{l} m = 0 \rightarrow \text{proton} \\ m = 1 \rightarrow \text{neutron} \end{array} \right\} \Rightarrow M_n > M_p$$

Meeting both approaches: Equivalent states \Rightarrow same energies

- Hamiltonian 1

$$H_{\text{rot}} = \frac{1}{2} \left[\frac{\mathcal{I}_1}{\mathcal{I}_1 \mathcal{J}_1 - \mathcal{K}_1^2} l(l+1) + \frac{\mathcal{J}_1}{\mathcal{I}_1 \mathcal{J}_2 - \mathcal{K}_1^2} k(k+1) \right. \\ \left. + \left(\frac{1}{\mathcal{I}_3} - \frac{\mathcal{I}_1 + \mathcal{J}_1 - 2\mathcal{K}_1}{\mathcal{I}_1 \mathcal{J}_1 - \mathcal{K}_1^2} \right) k_3^2 \right] + \frac{\mathcal{K}_1}{\mathcal{I}_1 \mathcal{J}_1 - \mathcal{K}_1^2} \langle N | \vec{K} \cdot \vec{L} | N \rangle$$

- Hamiltonian 2

$$H_{\text{rot}} = \frac{1}{2} \left[\frac{\mathcal{K}_1}{\mathcal{I}_1 \mathcal{J}_1 - \mathcal{K}_1^2} m(m+1) + \frac{\mathcal{I}_1 - \mathcal{K}_1}{\mathcal{I}_1 \mathcal{J}_1 - \mathcal{K}_1^2} l(l+1) \right. \\ \left. + \frac{\mathcal{J}_1 - \mathcal{K}_1}{\mathcal{I}_1 \mathcal{J}_1 - \mathcal{K}_1^2} k(k+1) + \left(\frac{1}{\mathcal{I}_3} - \frac{\mathcal{I}_1 + \mathcal{J}_1 - 2\mathcal{K}_1}{\mathcal{I}_1 \mathcal{J}_1 - \mathcal{K}_1^2} \right) k_3^2 \right]$$

- Equivalence relation

$$m(m+1) - j(j+1) - i(i+1) = 2\langle N | \vec{K} \cdot \vec{L} | N \rangle = -2i_3 - \frac{1}{2}$$

- For $i = j = 1/2$

$$\alpha = \arccos[m(m+1) - 1]$$

$$m = 0 \Rightarrow \alpha = \arccos(-1) = \pi \rightarrow \text{proton?}$$

$$m = 1 \Rightarrow \alpha = \arccos(1) = 0 \rightarrow \text{neutron?}$$

Analysis:

- Four different states corresponding to $\alpha = \pi$ ($m = 0$) and other four states for $\alpha = 0$ ($m = 1$); possible combinations of i_3 and j_3 .

Analysis:

- Four different states corresponding to $\alpha = \pi$ ($m = 0$) and other four states for $\alpha = 0$ ($m = 1$); possible combinations of i_3 and j_3 .
- Proton and neutron states: Finkelstein-Rubinstein constraints killing non-desirable states...

Analysis:

- Four different states corresponding to $\alpha = \pi$ ($m = 0$) and other four states for $\alpha = 0$ ($m = 1$); possible combinations of i_3 and j_3 .
- Proton and neutron states: Finkelstein-Rubinstein constraints killing non-desirable states...
- ... but it does not seem possible: body-fixed operators.

Analysis:

- Four different states corresponding to $\alpha = \pi$ ($m = 0$) and other four states for $\alpha = 0$ ($m = 1$); possible combinations of i_3 and j_3 .
- Proton and neutron states: Finkelstein-Rubinstein constraints killing non-desirable states...
- ... but it does not seem possible: body-fixed operators.
- Conclusion: the Hamiltonian does not distinguish third components of spin and isospin \Rightarrow Four ground states and four excited states.

Analysis:

- Four different states corresponding to $\alpha = \pi$ ($m = 0$) and other four states for $\alpha = 0$ ($m = 1$); possible combinations of i_3 and j_3 .
- Proton and neutron states: Finkelstein-Rubinstein constraints killing non-desirable states...
- ... but it does not seem possible: body-fixed operators.
- Conclusion: the Hamiltonian does not distinguish third components of spin and isospin \Rightarrow Four ground states and four excited states.
- Effect of the isospin-breaking potential? To break the spherically symmetric solitons to axial ones (related to the body-fixed operators).

Conclusions

- Breaking of the isospin symmetry: Distinction between proton and neutron, binding energies.
- Long story: More than 4 years and three different attempts.
- Perturbative isospin-breaking potential:
 - Constant contribution to the energy.
- Covariant derivative approach:
 - Inclusion of isospin chemical potential (in-medium Skyrmions).
 - Not well-defined formalism.
- Isospin-broken solution:
 - Exact $B = 1$ solution for an isospin-breaking potential.
 - Axially symmetric soliton instead of spherical one.
 - No distinction between third components of isospin.

Please tell me and let us write the script



$\partial_2 \phi + i g \phi \cdot \mathbf{A} = 0$